Correction

Andrews, Steven S. and Adam P. Arkin. 2007. A mechanical explanation for cytoskeletal rings and helices in bacteria. *Biophys. J.* 93:1872-1884.

In the appendix, equation 18 and the preceding text should read:

The yaw, pitch, and roll angles are

$$a_{\phi} = \operatorname{Atan} \frac{\operatorname{s} a' \operatorname{c} \chi}{\operatorname{c} a' \operatorname{c}^{2} \chi - \operatorname{s}^{2} \chi}, \ a_{\theta} = \operatorname{Asin} \left(-\operatorname{c} a' \operatorname{c} \chi \operatorname{s} \chi - \operatorname{s} \chi \operatorname{c} \chi \right), \text{ and}$$

$$a_{\psi} = \operatorname{Atan} \frac{-\operatorname{s} a' \operatorname{s} \chi}{-\operatorname{c} a' \operatorname{s}^{2} \chi + \operatorname{c}^{2} \chi}. \tag{18}$$

The second of these equations, a_{θ} was presented incorrectly before. This is simply a typographical error, so it does not affect any of the other equations in the article or any of our conclusions. The authors apologize for this error and any inconvenience it might have caused the readers of the *Biophysical Journal*.